

## Rotary indexing tables DHTG

FESTO



# Rotary indexing tables DHTG

Key features

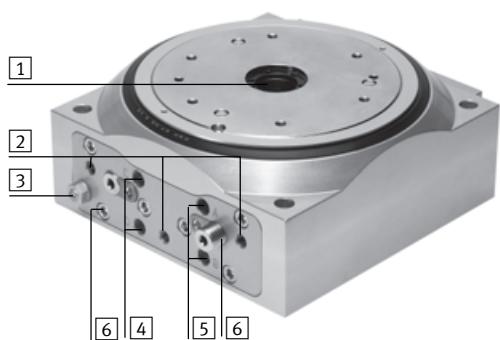
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## At a glance

- Sturdy mechanical system
- Easy planning and commissioning
- Indexing: 2, 3, 4, 6, 8, 12, 24
- Integrated functions:
  - Overload protection
  - Sensor function
  - Cushioning adjustment
- Speed setting
- Changing the direction of rotation

## The technology in detail

- |   |  |
|---|--|
| [1] Through-hole for energy throughfeed             | [4] Supply port for reciprocating motion                 |
| [2] Thread for position sensing                     | [5] Supply port for clockwise or anti-clockwise rotation |
| [3] One-way flow control valve for regulating speed | [6] Adjusting screw for cushioning adjustment            |



## Control options

Clockwise

- Just one valve required



Anticlockwise

- Just one valve required



Reciprocating motion

- After conversion with a reciprocating motion kit
- Two valves required



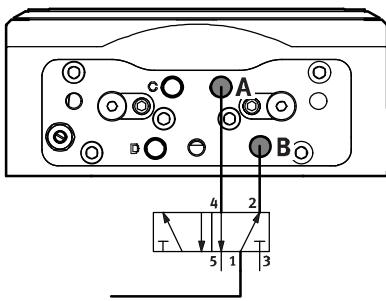
Flexible control:  
Clockwise, anticlockwise,  
reciprocating motion

- After conversion with a reciprocating motion kit
- Two valves required

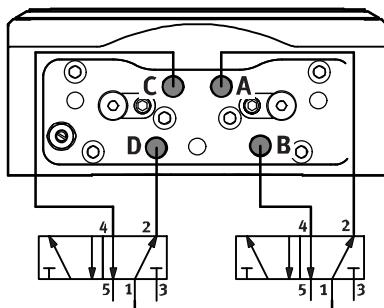


## Examples for simple interfaces

Clockwise/anticlockwise



Reciprocating motion/flexible control



# Rotary indexing tables DHTG

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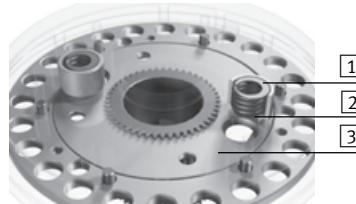
## Key features

### The technology in detail

#### Overload protection

To prevent the rotary indexing table from being damaged by an excessive mass moment of inertia, e.g. during setting operation or in the event of shock absorber failure, sizes 140 and 220 feature overload protection. If the mass moment of inertia is too large, the securing pin is pressed against the spring force by the result-

ing radial force. It then slides forward on the toothed segment. This shift in position between the index plate and toothed segment means that the securing pin can no longer engage and the rotary indexing table does not move. The table can be made ready for use again by turning it back.



- [1] Securing pin
- [2] Spring
- [3] Toothed segment

#### Energy throughfeed

Electrical signals or compressed air can be transferred through the hollow shaft using the energy throughfeed. This enables fast and easy supply of the parts connected to the rotary table.

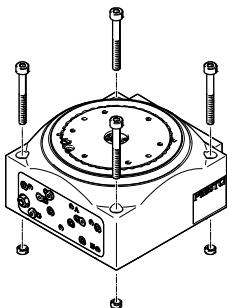
Also suitable for IO-Link signal data transfer.

- [1] Electrical connection (output)
- [2] Housing, energy throughfeed
- [3] Supply port (output)
- [4] Rotary indexing table
- [5] Supply port (input)
- [6] Electrical connection (input)

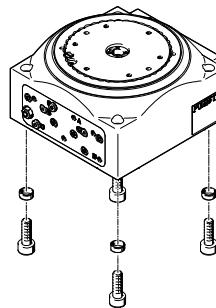


### Mounting options

#### Direct mounting from above



#### Direct mounting from below



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## Application examples

### Basic rotary table

- Handling with minimum space requirement



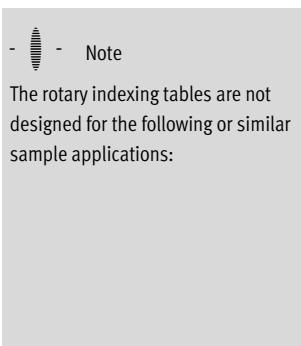
### Rotary table with rotary distributor

- For the transfer of compressed air and vacuum to the rotary table
- With 1 or 2 separate ducts



### Rotary table with stationary centre section

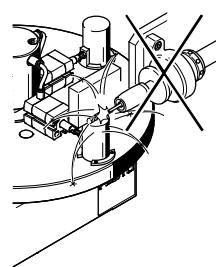
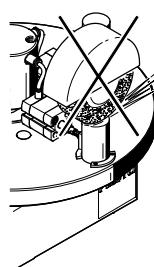
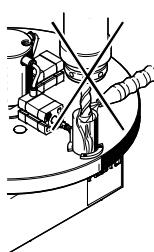
- For the mounting of handling units or other devices in the centre of the rotary indexing table



- Machining
- Aggressive media

- Grinding dust

- Welding spatter



# Rotary indexing tables DHTG

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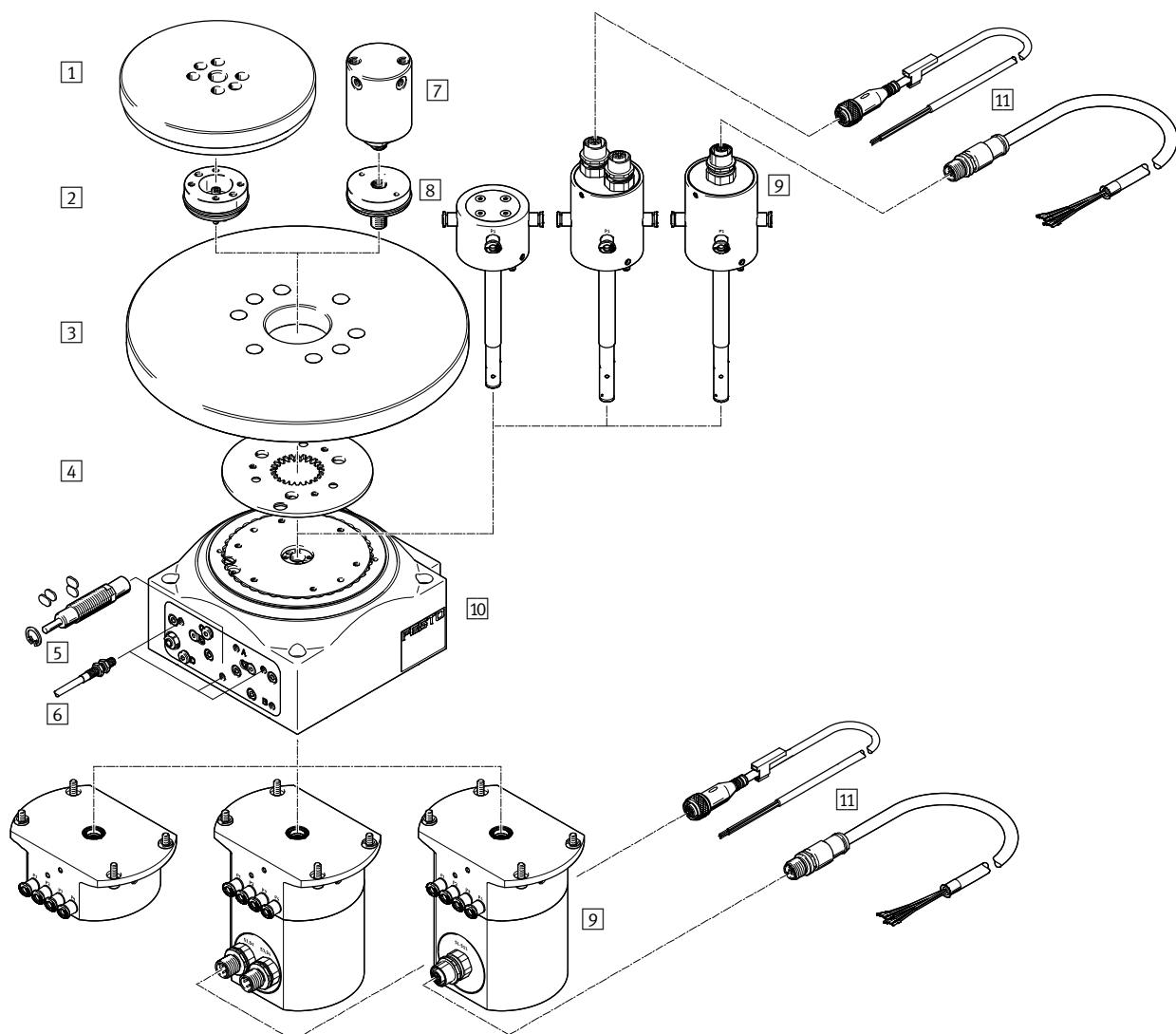
Type codes

DHTG	90	8	A					
<b>Series</b>								
DHTG	Rotary indexing table							
<b>Size</b>								
<b>Indexing</b>								
<b>Position sensing</b>								
A	Via proximity sensor							
<b>Energy throughfeed</b>								
-	None							
P4	Pneumatic, 4 ducts							
P4E4	Pneumatic, 4 ducts electric, 4 signals							
P4L12	Pneumatic, 4 ducts electric, 12 cables							

# Rotary indexing tables DHTG

Peripherals overview

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# Rotary indexing tables DHTG

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Peripherals overview

Variants and accessories		➔ Page/Internet
Type	Description	
[1] Plate, fixed	For illustration purposes only, not included in the scope of delivery	28
[2] Adapter kit DADG-AK	For mounting a blank plate on the rotary indexing table	28
[3] Plate, rotary	For illustration purposes only, not included in the scope of delivery	28
[4] Indexing conversion kit DADM-CK	The step angles can be adjusted at any time using the kit	30
[5] Reciprocating motion kit DADM-TK	Allows conversion from movement in one direction to reciprocating motion	30
[6] Proximity sensor SIEN	For sensing the switching position of the rotary indexing table	30
[7] Rotary distributor GF	Distributes the compressed air fed through the centre of the rotary indexing table to the actuators on the rotating blank plate. Cannot be used in combination with a fixed blank plate	29
[8] Adapter kit DADG-AK-...-G...	For mounting the rotary distributor on the rotary indexing table	29
[9] Pneumatic/electric energy throughfeed	For quick and easy pneumatic/electrical supply of parts connected to the rotary plate	12
[10] Rotary indexing table DHTG	Flexible application range: anticlockwise rotation, clockwise rotation or reciprocating motion	8
[11] Connecting cables NEBU, NEBS	For transmitting the signals	31

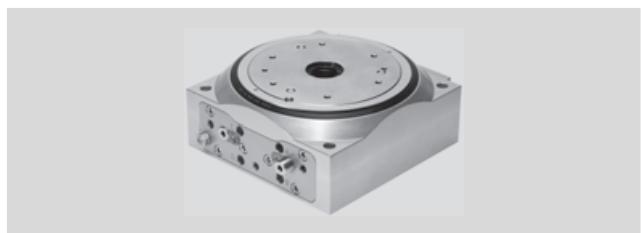
# Rotary indexing tables DHTG

Technical data

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- Ø - Size  
65, 90, 140, 220

Indexing  
2, 3, 4, 6, 8, 12, 24



General technical data					
Size	65	90	140	220	
Pneumatic connection	M5		G1/8		
Design	Gear coupling Rack and pinion Force pilot operated motion sequence				
Mode of operation	Double-acting				
Type of mounting	Via through-hole and centring sleeve				
Mounting position	Any				
Cushioning	Adjustable shock absorber stroke, hard characteristic curve				
Indexing	2, 3, 4, 6, 8, 12, 24		3, 4, 6, 8, 12, 24		
Torque at 6 bar [Nm]	2.1	4.4	18.1	58.9	
Parallelism of plate <sup>1)</sup> [mm]	≤ 0.04				
Axial eccentricity of plate <sup>2)</sup> [mm]	≤ 0.02				
Concentricity of plate <sup>3)</sup> [mm]	≤ 0.02				
Repetition accuracy of swivel angle [°]	≤ 0.03				
Max. mass moment of inertia without flow control <sup>4)</sup> [kgm <sup>2</sup> ]	0.016	0.03	0.3	2.5	
Cycle time without flow control	→ page 10				
Position sensing	Via inductive proximity sensors				
Weight					
DHTG-...	[kg]	2.0	4.5	10	24
DHTG-...-P4	[kg]	4.39	6.89	12.49	26.64
DHTG-...-P4E4	[kg]	5.12	7.62	13.22	27.37
DHTG-...-P4L12	[kg]	5.15	7.65	13.25	27.40

1) Parallelism of plate surface to housing support

2) Measured on the surface of the plate at the edge of the plate in relation to the housing support

3) Measured on the inner diameter of the plate in relation to the housing

4) Operation with flow control can increase the mass moment of inertia by 50%. The service life of the shock absorber is reduced in this case. The mass moment of inertia depends on the number of stations and the switching frequency (→ page 11)

- - Note

The "clockwise" rotation of the table can be controlled via an internal flow control valve in combination with the reciprocating motion kit. For "anti-clockwise" rotation, external actuation via an additional one-way flow control valve GRLA is needed.

Operating and environmental conditions	
Operating medium	Compressed air in accordance with ISO 8573-1:2010 [7:4:4]
Note on operating/pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Operating pressure [bar]	4 ... 8
Ambient temperature [°C]	5 ... 60
Storage temperature [°C]	-20 ... +80
Degree of protection	IP54 <sup>2)</sup>
Corrosion resistance class CRC <sup>1)</sup>	2

- 1) Corrosion resistance class CRC 2 to Festo standard FN 940070  
Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.
- 2) The specified degree of protection applies to the top side of the rotary indexing table. The underside must be provided with appropriate external protection for the environment.

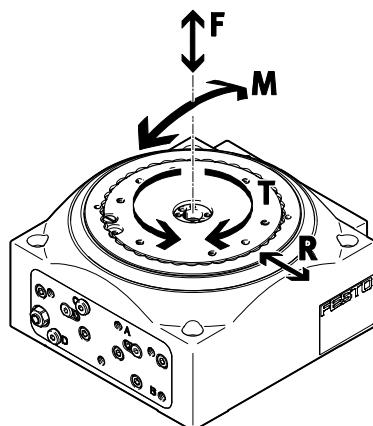
# Rotary indexing tables DHTG

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Technical data

## Static characteristic load values

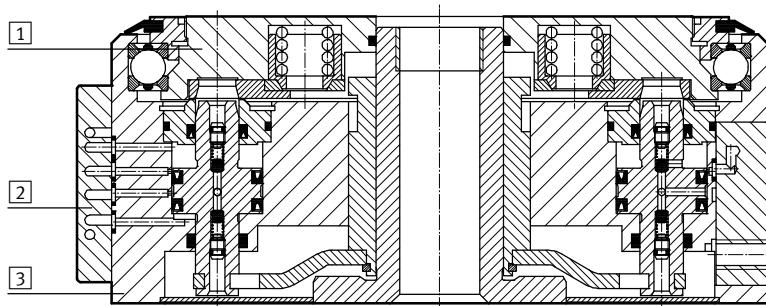
The indicated forces and torques refer to the locked table and can also act on the table plate.



Size	65	90	140	220
Forces				
Max. axial force F [N]	1000	2000	4000	5000
Max. radial force R [N]	2000	5000	6000	8000
Torque				
Max. tilting torque M [Nm]	100	150	300	500
Max. tangential torque T [Nm]	100	150	200	500

## Materials

Sectional view



## Rotary indexing table

[1] Plate	Galvanised steel
[2] Cap	Wrought aluminium alloy
[3] Housing	Wrought aluminium alloy
- Stops	Galvanised steel
- Seals	NBR, TPE-U (PU)

### Note on materials

DHTG-...	Free of copper and PTFE
DHTG-...-P4...	Cables with PTFE insulation
	Contains paint-wetting impairment substances

# Rotary indexing tables DHTG

Technical data

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## Calculation of the cycle time

The rotary indexing tables are equipped with a hydraulic shock absorber, which means that the max. frequency of the shock absorber must also be taken into account when calculating the cycle time.

The switching time comprises:  
Switching time = Unlock, rotate, lock and return stroke of working piston.  
The cycle time is calculated as follows:  
$$\text{Cycle time} = \text{Switching time} + \text{Processing time} + \text{Dwell time.}$$

In the switching frequency graph, the max. achievable switching frequency is read in relation to the mass moment of inertia. The switching time can be calculated from this as follows:  
$$T = 60/f$$
. The processing time is calculated from the time required by

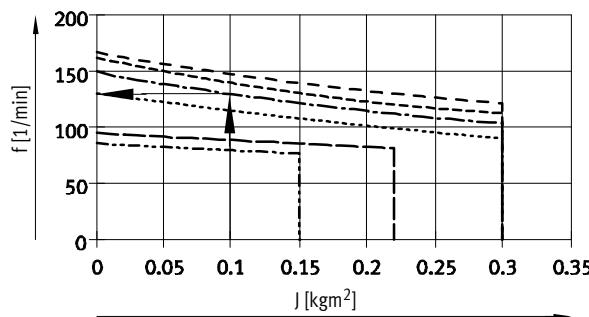
the respective customer application (e.g. time for component removal, press-in time, etc.). A dwell time may be necessary if the cycle time is shorter than the min. possible cycle time.

## Calculation example

DHTG-140 with 8 indexing stations and a mass moment of inertia of  $0.1 \text{ kgm}^2$ .

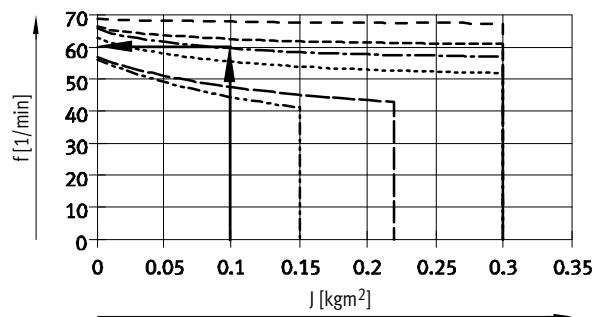
The customer application requires 300 ms per step for the insertion and removal of parts.

### Switching frequency



$$T_{\text{Switchingtime}} = \frac{1}{f} = \frac{60\text{s}}{130} = 0.461\text{s} = 461\text{ms}$$

### Max. permissible cycle frequency



$$T_{\text{Min.permissiblecycletime}} = \frac{60\text{s}}{59} = 1.017\text{s} = 1017\text{ms}$$

Dwell time = Min. permissible cycle time – Switching time – Processing time

Dwell time = 1017 ms – 461 ms – 300 ms = 256 ms.

Given the fact that the switching time + processing time is shorter than the min. permissible cycle time, the rotary indexing table must stay in the end position

before the next step is performed. In other words, between the circuits an additional dwell time of 256 ms must be allowed for in the control sequence.

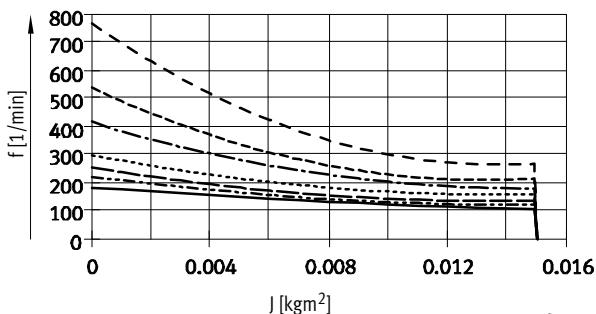
# Rotary indexing tables DHTG

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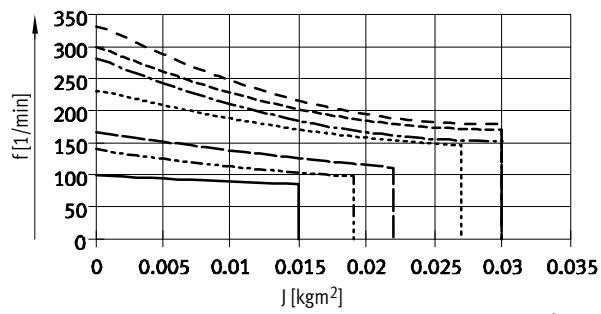
Technical data

Mass moment of inertia  $J$  as a function of switching frequency  $f$  and number of stations

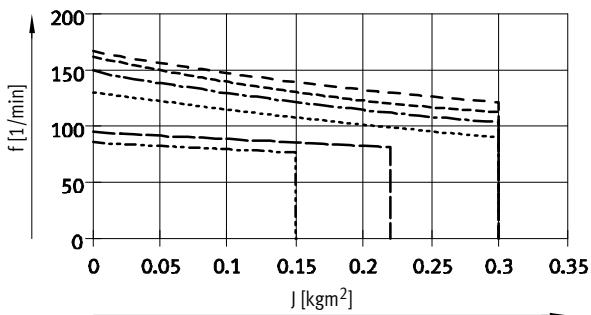
Size 65



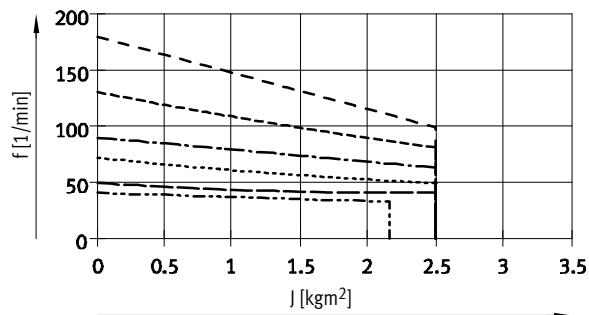
Size 90



Size 140

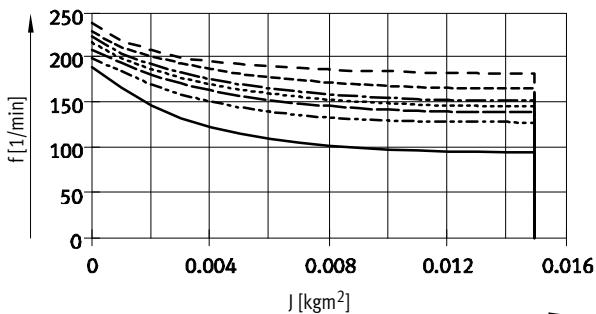


Size 220

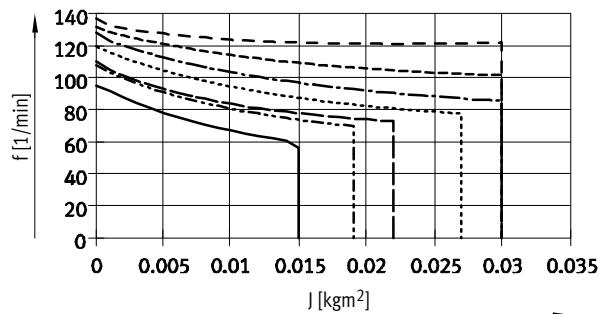


Max. permissible cycle frequency  $f$  as a function of mass moment of inertia  $J$

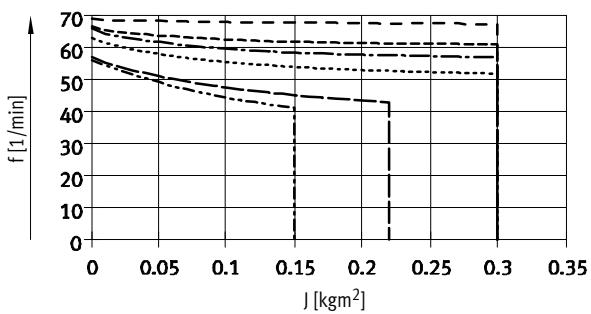
Size 65



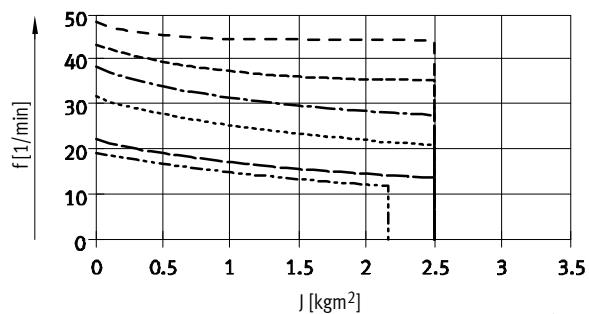
Size 90



Size 140



Size 220



- 2 indexing stations
- - - 3 indexing stations
- 4 indexing stations
- - - 6 indexing stations
- 8 indexing stations
- - - 12 indexing stations
- 24 indexing stations

# Rotary indexing tables DHTG

Technical data

## Energy throughfeed

DHTG-...-P4

DHTG-...-P4E4

DHTG-...-P4L12



### Function

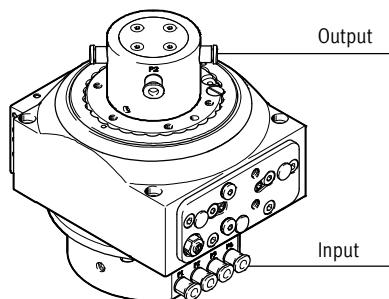
Electrical signals or compressed air can be transferred through the hollow shaft using the energy throughfeed.

### Benefits

- Fast and easy supply of the parts connected to the rotary table
- Tubing and electrical cables are not damaged by the rotation
- Two variants available:
  - Pneumatic
  - Pneumatic and electrical

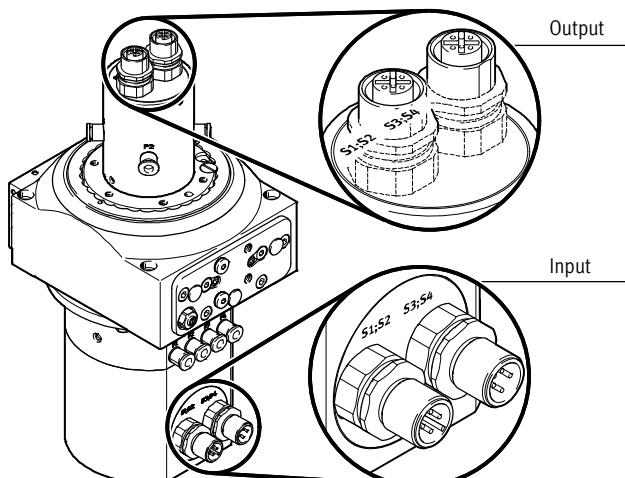
### Pneumatic

DHTG-...-P4

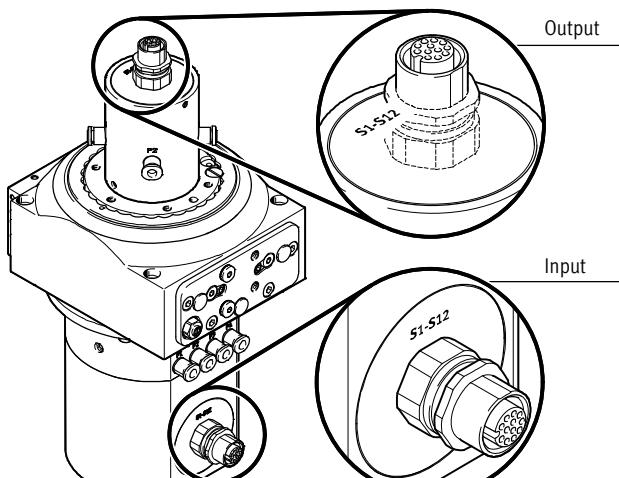


### Pneumatic/electrical

DHTG-...-P4E4



### DHTG-...-P4L12



# Rotary indexing tables DHTG

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Technical data

Technical data			
Variant	Pneumatic	Pneumatic/electrical	Pneumatic/electrical
Order code	P4	P4E4	P4/L12
Pneumatic			
Number of pneumatic ducts	4	4	4
Tubing O.D.	4		
Max. operating pressure [bar]	8		
Connection	M5		
Flow rate per duct [l/min.]	86		
Electrical			
Number of signal lines	-	4	12 <sup>1)</sup>
Rated voltage [DC V]	-	30	30
Max. current <sup>1)</sup> [A]	-	1.5	1.5
Cable cross section [mm <sup>2</sup> ]	-	0.14	0.14
Connection	-	M12	M12

1) Freely configurable

## Pin allocation – Energy throughfeed, electrical

DHTG....-P4E4

Input				Output			
M12 plug				M12 socket			
Designation	Pin allocation	Pin	Circuit diagram	Circuit diagram	Pin	Pin allocation	Designation
S1;S2	+	1			1	+	S1; S2
	Sig 2	2			2	Sig 2	
	-	3			3	-	
	Sig 1	4			4	Sig 1	
S3;S4	+	1			1	+	S3; S4
	Sig 4	2			2	Sig4	
	-	3			3	-	
	Sig 3	4			4	Sig 3	

DHTG....-P4L12

Input		Output	
M12 socket		M12 socket	
Designation	Circuit diagram	Circuit diagram	Designation
Sig 1 ... 12 freely configurable			Sig 1 ... 12 freely configurable

- - Note

Only connecting cables with straight connectors can be used (→ 31).

# Rotary indexing tables DHTG

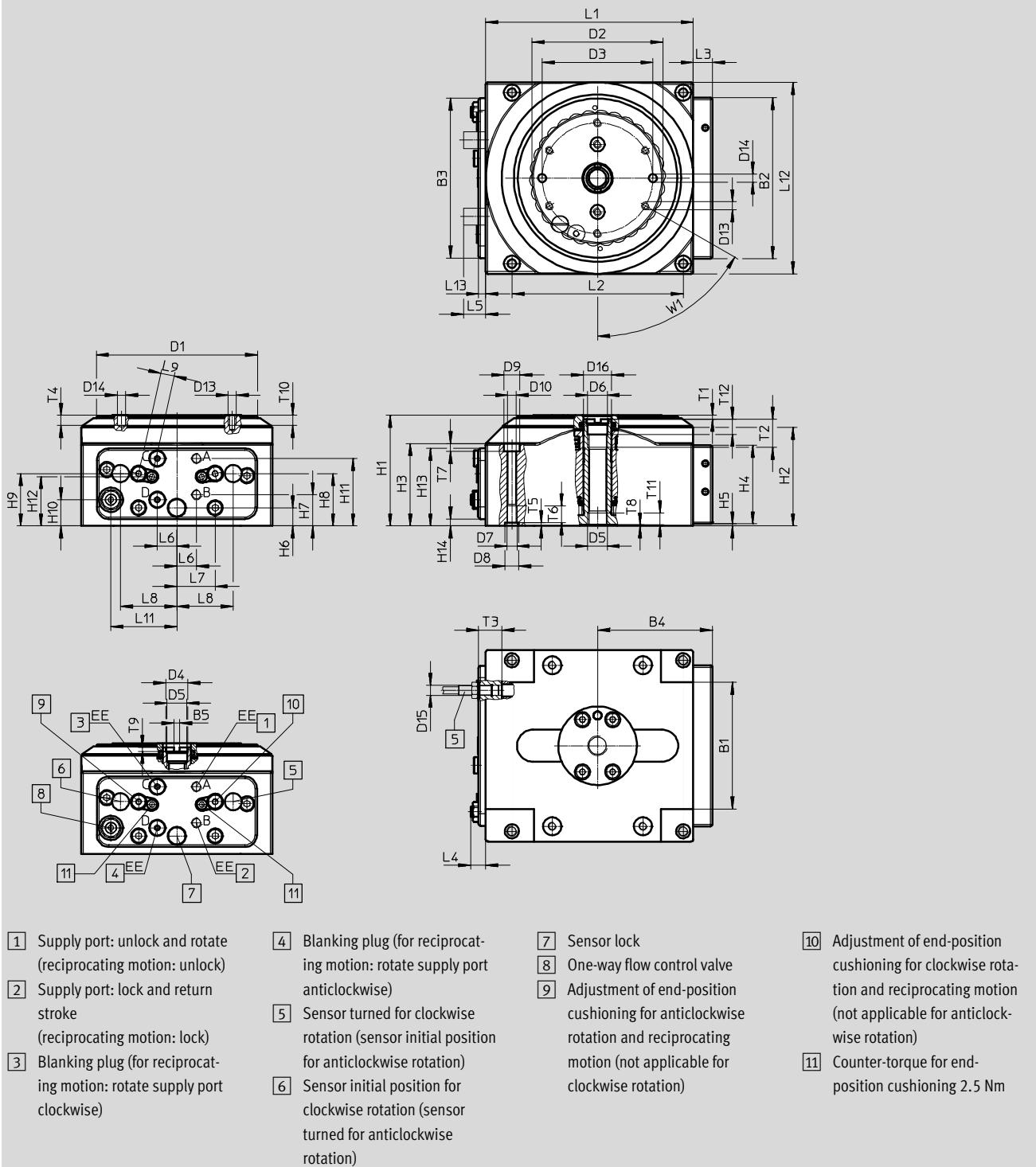
Technical data

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## Dimensions

Size 65

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## Rotary indexing tables DHTG

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Technical data

Size	B1 <sup>3)</sup> ±2	B2	B3	B4	B5 +0.1	D1 Ø	D2 Ø	D3 <sup>1)</sup> Ø	D4 Ø	D5	D6 Ø H8	D7
65	63	80	79.5	47.5	3	80	65	55	11	6 1/8	10	M5

Size	D8 Ø H8	D9 Ø	D10 Ø	D13	D14 Ø H8	D15	D16 Ø H8	EE	H1 ±0.5	H2	H3	H4
65	7	8	4.3	M4	4	M5x0.5	14	M5	55	49	41	39

Size	H5	H6	H7	H8	H9	H10	H11	H12	H13	H14	L1 ±0.1	L2 <sup>1)</sup> □
65	1	9	15.5	26	26	13	33.5	24.5	38.5	3.5	103	85

Size	L3 +1	L4 Max.	L5 <sup>2)</sup>	L6	L7	L8	L9	L11	L12 ±0.1	L13 +0.1	T1 ±1	T2 Min.
65	9.5	7.5	11	9.75	19	28	6.75	32.75	95	3.5	2	14

Size	T3 Min.	T4 Min.	T5 +0.1	T6 Min.	T7	T8	T9	T10	T11 Min.	T12 Min.	W1
65	12	5	1.6	10	4	0.5	2	6	5	7	60°

1) Tolerance between the centring holes: ±0.02

Tolerance between the threaded holes and countersinks: ±0.2

2) Max. projection of shock absorber adjustment

3) 0.1 +0.05 recessed

# Rotary indexing tables DHTG

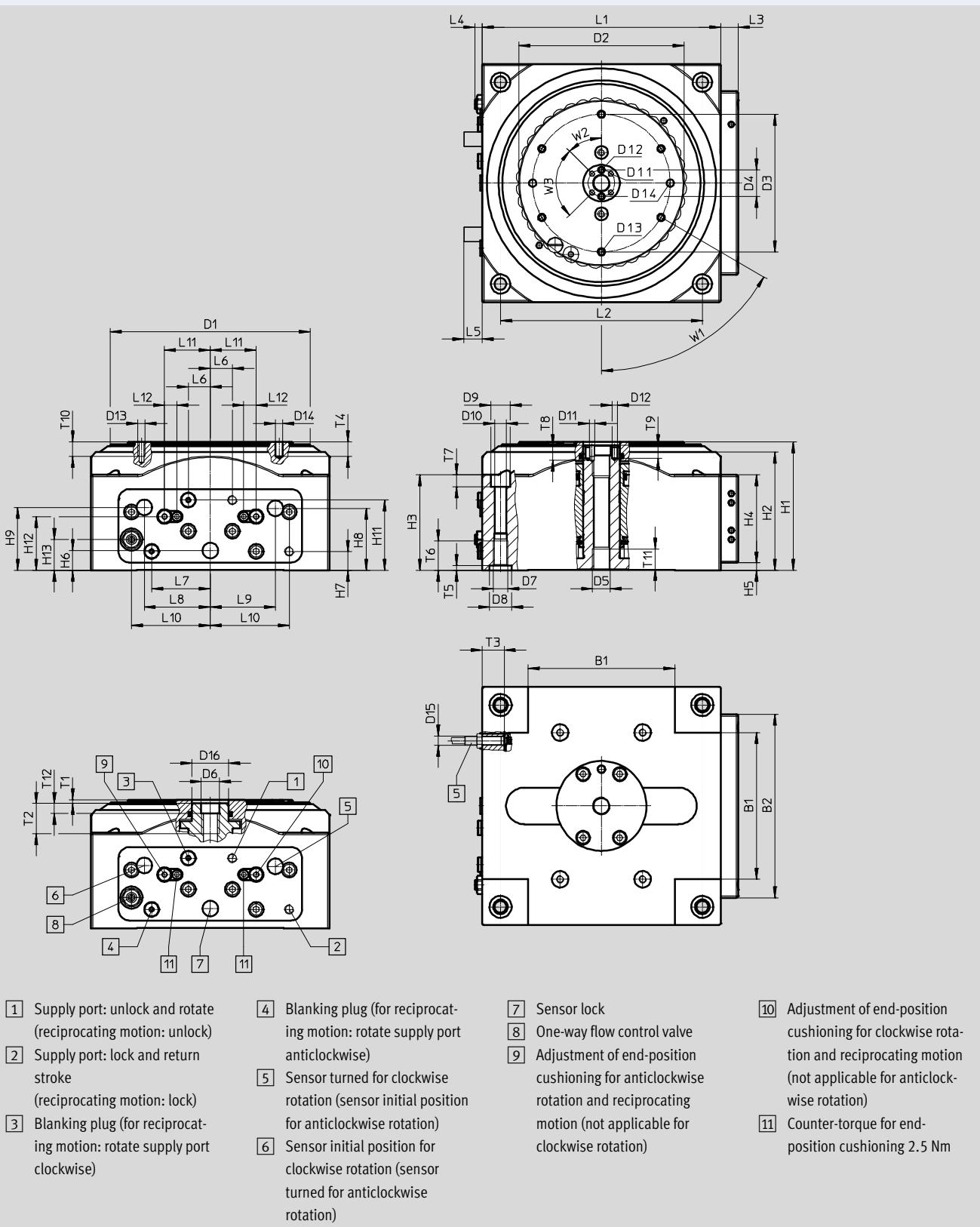
Technical data

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## Dimensions

Size 90

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## Rotary indexing tables DHTG

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Size	B1 <sup>3)</sup> ±2	B2	D1 ∅	D2 ∅	D3 <sup>1)</sup> ∅	D4 <sup>1)</sup> ∅	D5	D6 ∅ H8	D7	D8 ∅ H8	D9 ∅	D10 ∅
90	80	100	109	90	75	14.5	G1/8	10	M 8	12	10.5	6.4

Size	D11 ∅ H8	D12 ∅	D13 H8	D14 ∅	D15	D16 ∅ H8	EE	H1 ±0.5	H2	H3	H4	H5
90	M3	3	M4	4	M5x0.5	20	M5	70	64.4	52	48	4

Size	H6	H7	H8	H9	H11	H12	H13	L1 □ ±0.1	L2 <sup>1)</sup> □	L3	L4	L5 <sup>2)</sup> Max.
90	10.75	10.25	33.75	34.25	38.25	29.25	16.75	130	110	9.5	4	10

Size	L6	L7	L8	L9	L10	L11	L12	T1 ±1	T2 Min.	T3	T4 Min.
90	12	32	36	35.5	43	25	6.7	2	16.5	12	8

Size	T5 +0.1	T6 Min.	T7	T8	T9 Min.	T10 Min.	T11 Min.	T12	W1	W2	W3
90	2.6	16	6.5	6	5	8	11	5.5	60°	45°	90°

1) Tolerance for centring hole ±0.02 mm.

Tolerance for thread ±0.1 mm.

2) Max. projection of shock absorber adjustment

3) 0.1 +0.05 recessed

# Rotary indexing tables DHTG

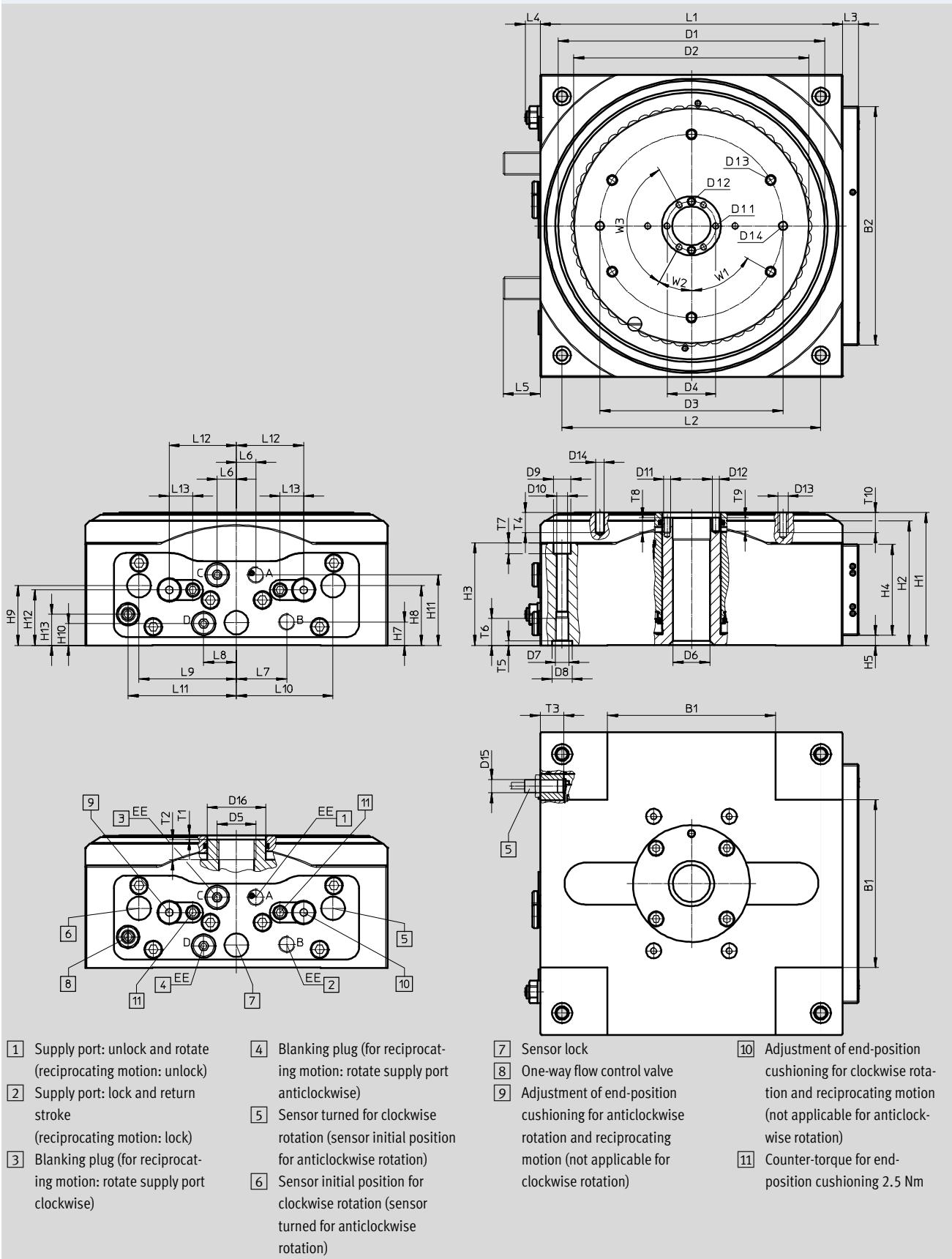
Technical data

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## Dimensions

Sizes 140, 220

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## Rotary indexing tables DHTG

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Technical data

Size	B1 <sup>3)</sup> ±2	B2	D1 Ø	D2 Ø	D3 <sup>1)</sup> Ø	D4 <sup>1)</sup> Ø	D5	D6 Ø	D7	D8 Ø	D9 Ø	D10 Ø	D11	D12 Ø	
140	100	142	159	140	109	29	M23x1	22	M 8	12	10.5	6.4	M4	4	
220	150	212	239	220	165	67	-	58.4	M10	15	13.5	8.4	M5	5	
Size	D13	D14 Ø	D15 H8	D16 Ø	EE	H1	H2	H3	H4	H5	H6	H7	H8	H9	
140	M6	5	M8x1	35	G1/8	79	74	61	54	6	13.5	14	35.5	35.5	
220	M 8	6	M8x1	75	G1/8	89	83.5	68.5	64	4.5	13.5	24.5	15	15	
Size	H10	H11	H12	H13	L1 □ ±0.1	L2 <sup>1)</sup> □	L3	L4	L5 <sup>2)</sup> Max.	L6	L7	L8	L9	L10	L11
140	13	42	33	18.5	180	154	9.5	8.9	22	11.5	30	19.5	58	57.5	64.5
220	24.5	50.5	36.5	24	270	228	12	4.6	22	41	41	41	61	61	99.5
Size	L12	L13	T1	T2	T3	T4	T5	T6	T7	T8	T9	T10	W1	W2	W3
			±1	Min.	Min.	Min.	+0.1	Min.		Min.	Min.	Min.			
140	40	14	3	12	14	8	2.6	16	6.5	8	8	11	60°	30°	120°
220	68	14	4	-	19	8	3.1	20	8.5	10	10	11	60°	30°	120°

1) Tolerance between the centring holes: ±0.02

Tolerance between the threaded holes and countersinks: ±0.2

2) Max. projection of shock absorber adjustment

3) 0.1 +0.05 recessed

# Rotary indexing tables DHTG

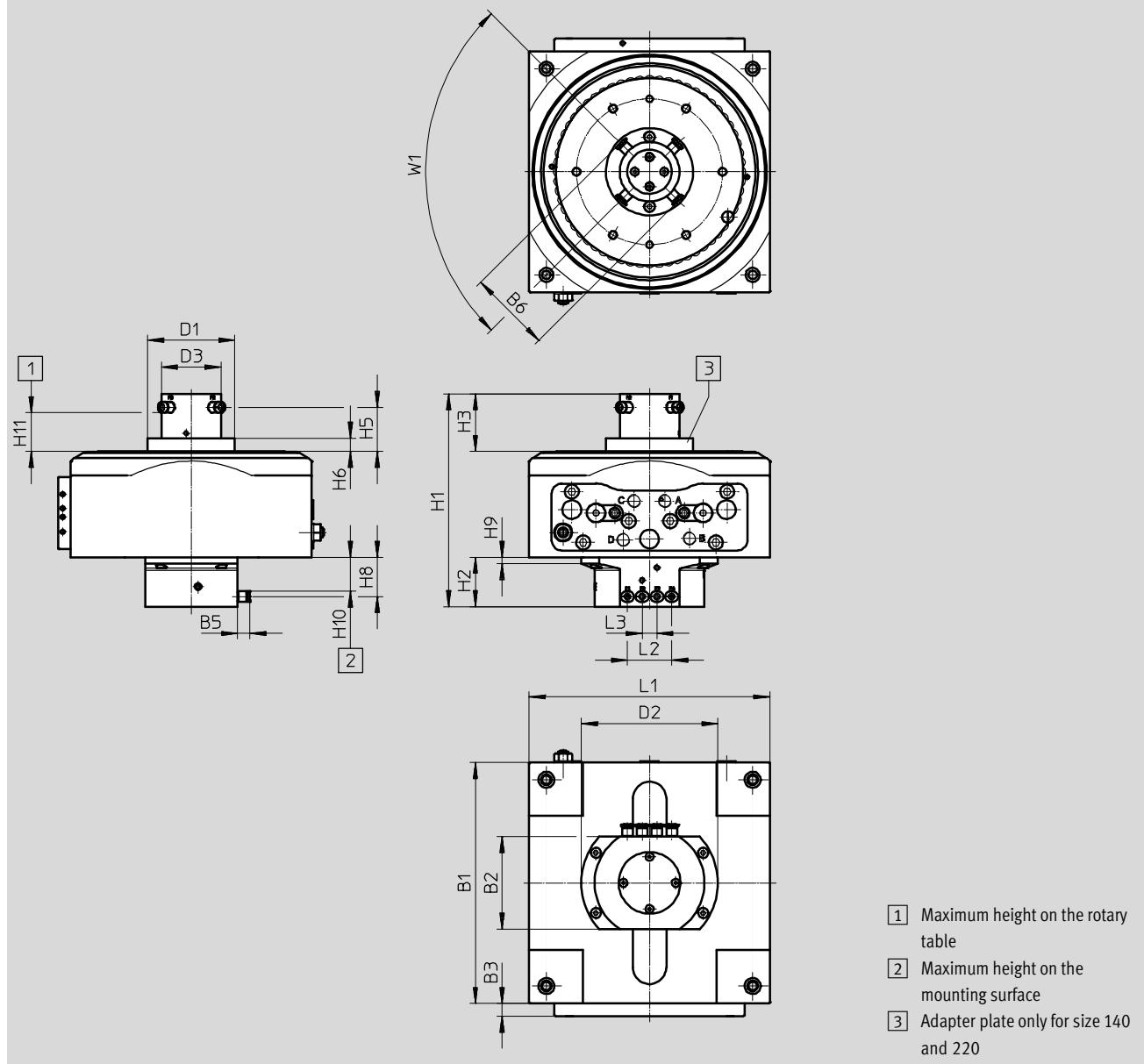
Technical data

FESTO

## Dimensions – Variants

P4 – Pneumatic energy throughfeed

Download CAD data → [www.festo.com](http://www.festo.com)



# Rotary indexing tables DHTG

**FESTO**

Technical data

Size	B1	B2 ±0.1	B3	B5	B6	D1 Ø ±0.1	D2 Ø
65	103		9.5			-	
90	130		9.5			-	
140	180		9.5			65	
220	270		12			100	

Size	D3 Ø ±0.1	H1	H2 ±0.1	H3	H5	H6 ±0.1	H8 ±0.1
65		125		33±0.1	23±0.05	-	
90		140		33±0.1	23±0.05	-	
140		159		43±0.2	33±0.15	10	
220		169		43±0.2	33±0.15	10	

Size	H9	H10	H11	L1	L2 ±0.1	L3	W1
65			19	95			
90			19	130			
140			29	180			
220			29	270			

# Rotary indexing tables DHTG

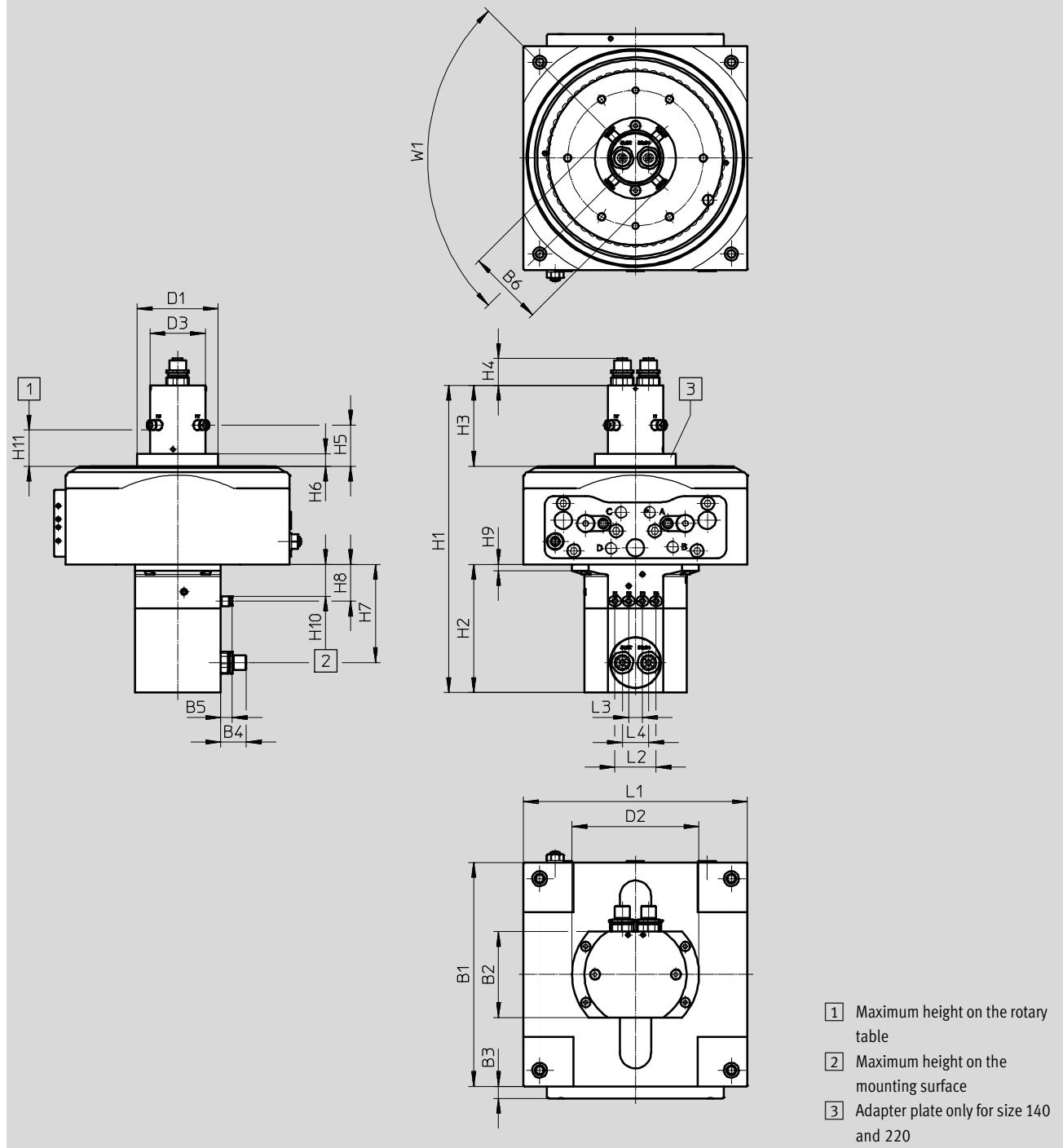
Technical data

FESTO

## Dimensions – Variants

P4E4 – Pneumatic/electrical energy throughfeed

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## Rotary indexing tables DHTG

**FESTO**

Technical data

Size	B1	B2 ±01	B3	B4 +3	B5	B6	D1 ∅ ±01	D2 ∅	D3 ∅ ±01
65	103	69	9.5	19	9.3	61.4	–	102	44.5
90	130		9.5				–		
140	180		9.5				65		
220	270		12				100		

Size	H1	H2 ±01	H3	H4 +2	H5	H6 ±01	H7	H8 ±01
65	213	103	55±0.1	17.5	23±0.05	–	79	29.5
90	228		55±0.1		23±0.05	–		
140	247		65±0.2		33±0.15	10		
220	257		65±0.2		33±0.15	10		

Size	H9	H10	H11	L1	L2 ±0.1	L3	L4	W1
65	5	25	19	95	33	11	21	90°
90			19	130				
140			29	180				
220			29	270				

# Rotary indexing tables DHTG

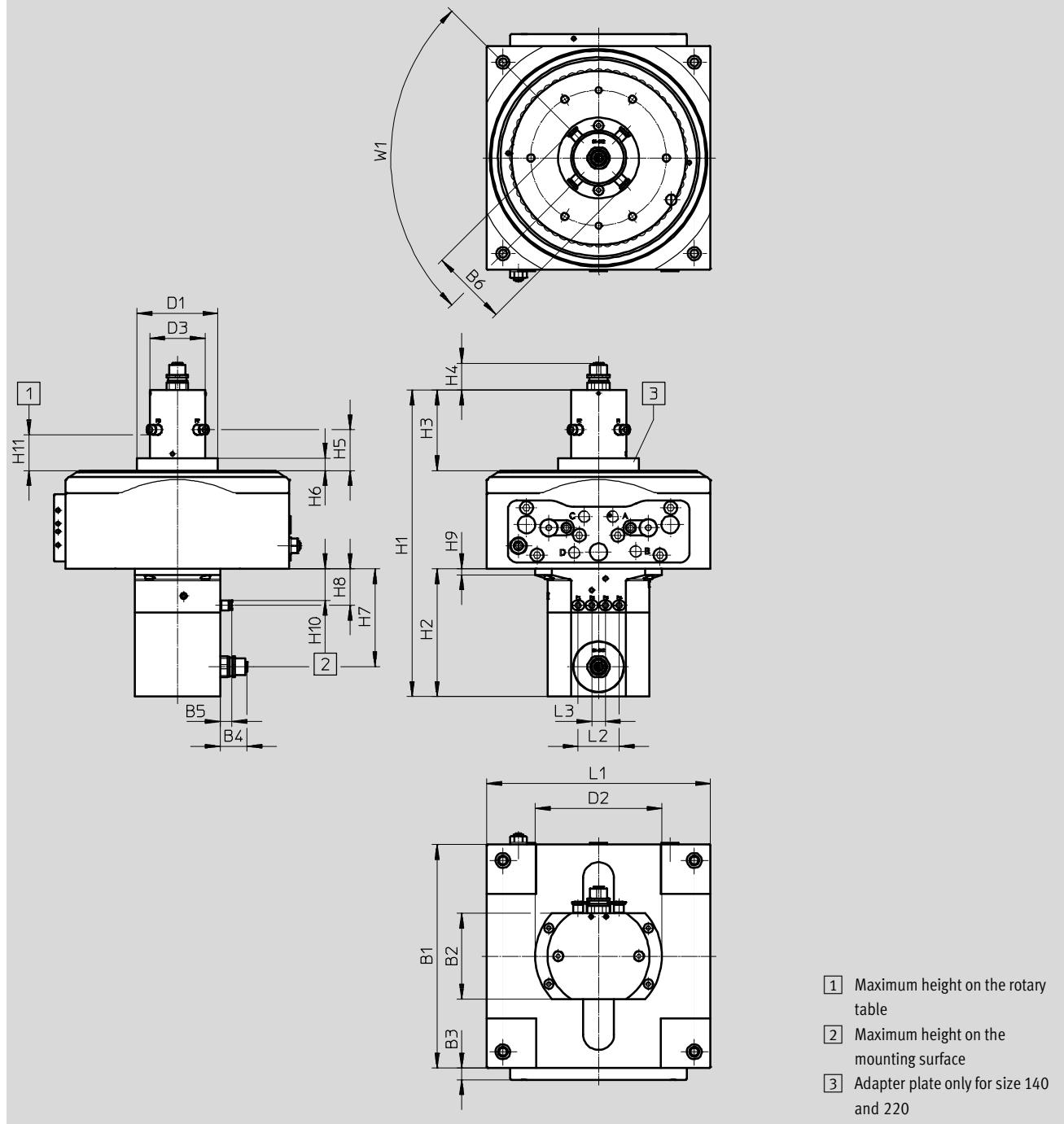
Technical data

FESTO

## Dimensions – Variants

P4L12 – Pneumatic/electrical energy throughfeed

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- [1] Maximum height on the rotary table
- [2] Maximum height on the mounting surface
- [3] Adapter plate only for size 140 and 220

## Rotary indexing tables DHTG

**FESTO**

Technical data

Size	B1	B2 ±0.1	B3	B4 +3	B5	B6	D1 ∅ ±0.1	D2 ∅
65	103	69	9.5	17.5	9.3	61.4	-	102
90	130		9.5					
140	180		9.5					
220	270		12					

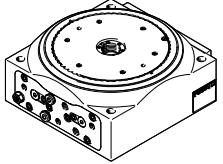
Size	D3 ∅ ±0.1	H1	H2 ±0.1	H3	H4 +2	H5	H6 ±0.1	H7
65	44.5	213	103	55±0.1	17.5	23±0.05	-	79
90		228		55±0.1		23±0.05	-	
140		247		65±0.2		33±0.15	10	
220		257		65±0.2		33±0.15	10	

Size	H8 ±0.1	H9	H10	H11	L1	L2 ±0.1	L3 ±0.1	W1
65	29.5	5	25	19	95	33	11	90°
90				19	130			
140				29	180			
220				29	270			

# Rotary indexing tables DHTG

Technical data

FESTO

Ordering data		Size	Indexing	Part No.	Type
	65	2	548076	DHTG-65-2-A	
		3	555448	DHTG-65-3-A	
		4	548077	DHTG-65-4-A	
		6	548078	DHTG-65-6-A	
		8	548079	DHTG-65-8-A	
		12	548080	DHTG-65-12-A	
		24	548081	DHTG-65-24-A	
	90	2	548082	DHTG-90-2-A	
		3	555449	DHTG-90-3-A	
		4	548083	DHTG-90-4-A	
		6	548084	DHTG-90-6-A	
		8	548085	DHTG-90-8-A	
		12	548086	DHTG-90-12-A	
		24	548087	DHTG-90-24-A	
	140	3	555450	DHTG-140-3-A	
		4	548088	DHTG-140-4-A	
		6	548089	DHTG-140-6-A	
		8	548090	DHTG-140-8-A	
		12	548091	DHTG-140-12-A	
		24	548092	DHTG-140-24-A	
		3	555451	DHTG-220-3-A	
	220	4	548093	DHTG-220-4-A	
		6	548094	DHTG-220-6-A	
		8	548095	DHTG-220-8-A	
		12	548096	DHTG-220-12-A	
		24	548097	DHTG-220-24-A	

## Rotary indexing tables DHTG

**FESTO**

Ordering data – Modular product system

Ordering table							
Size	65	90	140	220	Condi-tions	Code	Entry code
[M] Module no.	<b>575738</b>	<b>575739</b>	<b>575740</b>	<b>575741</b>			
Product type	DHTG G series					<b>DHTG</b>	DHTG
Size	65	90	140	220		-...	
Indexing	2 indexing stations		–			<b>-2</b>	
	3 indexing stations					<b>-3</b>	
	4 indexing stations					<b>-4</b>	
	6 indexing stations					<b>-6</b>	
	8 indexing stations					<b>-8</b>	
	12 indexing stations					<b>-12</b>	
	24 indexing stations					<b>-24</b>	
Position sensing	Via proximity sensor					<b>A</b>	A
[O] Energy throughfeed	None					<b>–</b>	
	Pneumatic, 4 ducts					<b>-P4</b>	
	Pneumatic, 4 ducts; electric, 4 signals					<b>-P4E4</b>	
	Pneumatic, 4 ducts; electric, 12 cables					<b>-P4L12</b>	

### Transfer order code

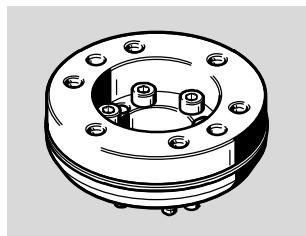
**DHTG**  -  -  - **A**

# Rotary indexing tables DHTG

Accessories

FESTO

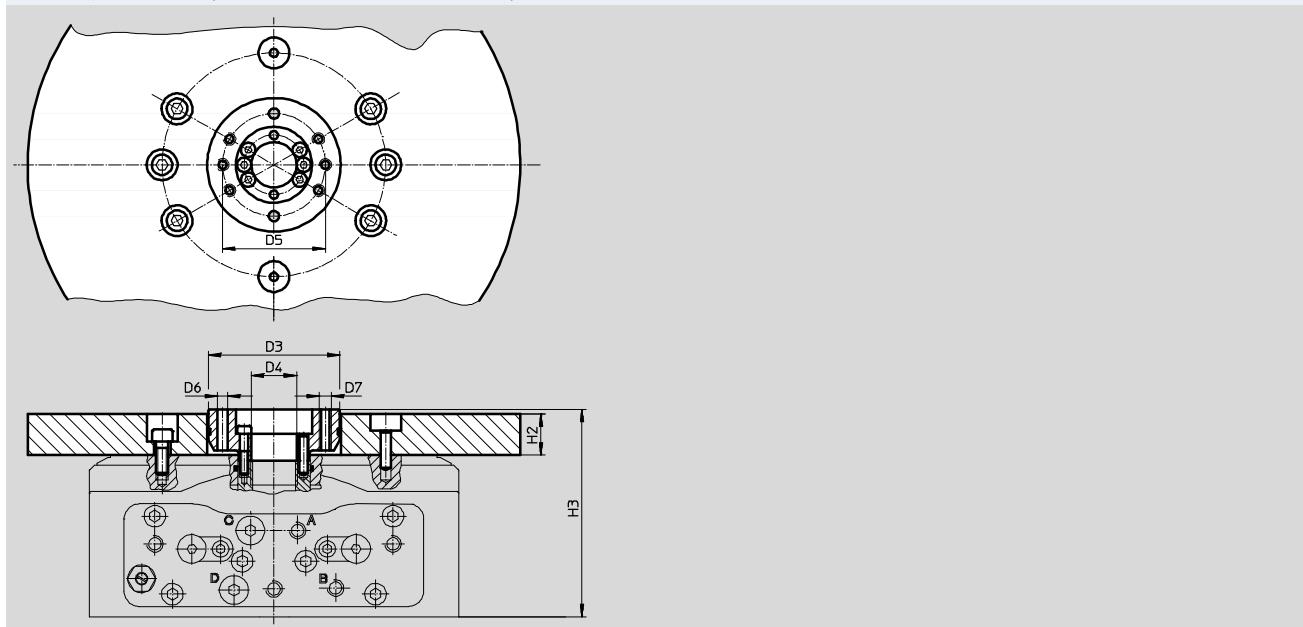
Adapter kit  
DADG-AK



## Dimensions

With rotary table and adapter kit DADG-AK for mounting a fixed plate

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Size	D3 ∅ +0.2	D4 ∅ +0.2	D5 ∅	D6 ∅ H7	D7	H2	H3
DADG-AK-65	29	5	20	4	M4	15	72
DADG-AK-90	39	9	30	4	M4	15	87
DADG-AK-140	64	22	50	5	M6	20	101
DADG-AK-220	104	58.4	90	6	M8	20	111

Ordering data – Adapter kit DADG-AK			
	For size	Part No.	Type
	65	555424	DADG-AK-65
	90	555425	DADG-AK-90
	140	555426	DADG-AK-140
	220	555427	DADG-AK-220

# Rotary indexing tables DHTG

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Accessories

## Rotary distributors

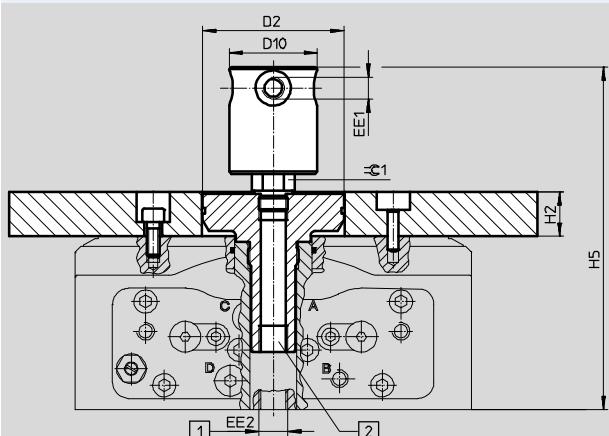
GF..., single

GF...-2, multiple



### Dimensions

With rotary distributor GF... (single) and adapter kit DADG-AK...

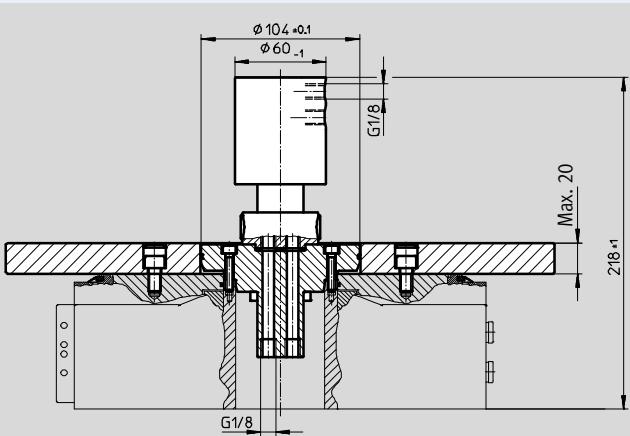


[1] External supply port for DHTG-65/90

[2] Internal supply port for DHTG-140/220

Download CAD data ➔ [www.festo.com](http://www.festo.com)

With rotary distributor GF-1/8-2 (multiple) and adapter kit DADG-AK-220-2G18  
– for size 220



Size	D2	D10 ∅ +0.2	EE1	EE2	H2	H5	⊖ 1
DADG-AK-65-1G18 GF-1/8-M5	29	40	M5	G1/8	15	127.5	17
DADG-AK-90-1G18 GF-1/8-M5	39	40	M5	G1/8	15	142.5	17
DADG-AK-140-1G14 GF-1/4-1/8	64	40	G1/8	G1/4	20	155.5	17
DADG-AK-220-1G12 GF-1/2-1/4	104	60	G1/4	G1/2	20	187.5	27

### Ordering data

Rotary distributor GF

	For size	Part No.	Type
	Simple		
	65, 90	<b>539290</b>	GF-1/8-M5
	140	<b>539291</b>	GF-1/4-1/8
	220	<b>539292</b>	GF-1/2-1/4
Multiple			
220	<b>539287</b>	GF-1/8-2	

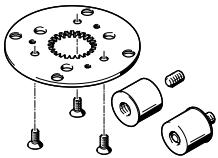
Adapter kit DADG-AK

	For size	Part No.	Type
	Simple		
	65	<b>555428</b>	DADG-AK-65-1G18
	90	<b>555429</b>	DADG-AK-90-1G18
	140	<b>555430</b>	DADG-AK-140-1G14
220	<b>555431</b>	DADG-AK-220-1G12	
Multiple			
220	<b>555432</b>	DADG-AK-220-2G18	

# Rotary indexing tables DHTG

Accessories

**FESTO**

Ordering data		For size	Indexing	Part No.	Type
Indexing conversion kit DADM-CK					
	65	2		548098	DADM-CK-65-2
		3		554389	DADM-CK-65-3
		4		548099	DADM-CK-65-4
		6		548100	DADM-CK-65-6
		8		548101	DADM-CK-65-8
		12		548102	DADM-CK-65-12
		24		548103	DADM-CK-65-24
	90	2		548104	DADM-CK-90-2
		3		555445	DADM-CK-90-3
		4		548105	DADM-CK-90-4
		6		548106	DADM-CK-90-6
		8		548107	DADM-CK-90-8
		12		548108	DADM-CK-90-12
		24		548109	DADM-CK-90-24
	140	3		555446	DADM-CK-140-3
		4		548110	DADM-CK-140-4
		6		548111	DADM-CK-140-6
		8		548112	DADM-CK-140-8
		12		548113	DADM-CK-140-12
		24		548114	DADM-CK-140-24
	220	3		555447	DADM-CK-220-3
		4		548115	DADM-CK-220-4
		6		548116	DADM-CK-220-6
		8		548117	DADM-CK-220-8
		12		548118	DADM-CK-220-12
		24		548119	DADM-CK-220-24
Reciprocating motion kit DADM-TK					
	65	-		548120	DADM-TK-65
				548121	DADM-TK-90
				563304	DADM-TK-140
				563305	DADM-TK-220

Ordering data – Proximity sensor, inductive					Technical data → Internet: sien
	For size	Contact	Connection	Part No.	Type
	65, 90	N/O contact	Plug	150371	SIEN-M5B-PS-S-L
		N/C contact	Plug	150375	SIEN-M5B-PO-S-L
	140, 220	N/O contact	Cable	150386	SIEN-M8B-PS-K-L
			Plug	150387	SIEN-M8B-PS-S-L
		N/C contact	Cable	150390	SIEN-M8B-PO-K-L
			Plug	150391	SIEN-M8B-PO-S-L

Ordering data – Connecting cables					Technical data → Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

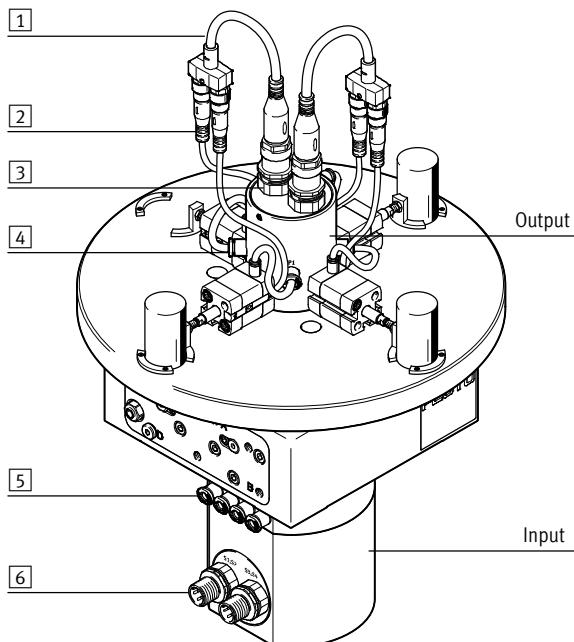
# Rotary indexing tables DHTG

FESTO

Accessories

## Wiring of the proximity sensor in combination with the energy throughfeed

Sample illustration using DHTG-...-P4E4



- [1] Y-distributor  
NEDY-L2R1-V1-...
- [2] Proximity sensor with plug
- [3] Electrical connection (output)
- [4] Supply port (output)
- [5] Supply port (input)
- [6] Electrical connection (input)



**Note**  
For variant DHTG-...-P4E4, proximity sensors with plugs must be used for the attachments at the output. These are then connected to the energy throughfeed module using a Y-distributor.

## Ordering data – Connecting cables for proximity sensor

	Electrical connection, left	Electrical connection, right	Suitable for use with energy chains	Cable length [m]	Part No.	Type
<b>DHTG-...-P4E4</b>						
<b>Input</b>						
	Straight socket, M12x1, 5-pin	Cable, open end, 4-wire	■	2.5	550326	NEBU-M12G5-K-2.5-LE4
				5	541328	NEBU-M12G5-K-5-LE4
<b>Output</b>						
	Straight plug, M12x1, 4-pin	2x straight sockets, M8x1, 3-pin	–	0.3 <sup>1)</sup>	8032867	NEDY-L2R1-V1-M8G3-U-M12G4-0.3R
<b>DHTG-...-P4L12</b>						
<b>Input/output</b>						
	Straight plug, M12x1, 12-pin	Straight plug, M12x1, 12-wire	■	0.3	3947404	NEBS-SM12G12-E-0.3-N-M12G12
		Cable, open end, 12-wire	■	0.5	3947401	NEBS-SM12G12-E-0.5-N-LE12
				5	3947395	NEBS-SM12G12-E-5-N-LE12

1) Cable lengths can be selected between 0.3 m and 30 m → Internet: nedy

## Ordering data – Rotary throughfeed

	Description	Part No.	Type
	Spare part for energy throughfeed. Can be replaced as needed.	3920687	DHAS-SCR12-H6

# Festo North America



**[1] Festo Canada Headquarters**  
**Festo Inc.**  
5300 Explorer Drive  
Mississauga, ON  
L4W 5G4

**[2] Montréal**  
5600, Trans-Canada  
Pointe-Claire, QC  
H9R 1B6

**[3] Québec City**  
2930, rue Watt#117  
Québec, QC  
G1X 4G3



**[4] Festo United States Headquarters**  
**Festo Corporation**  
395 Moreland Road  
Hauppauge, NY  
11788

**[5] Appleton**  
North 922 Tower View Drive, Suite N  
Greenville, WI  
54942

**[7] Detroit**  
1441 West Long Lake Road  
Troy, MI  
48098

**[6] Chicago**  
85 W Algonquin - Suite 340  
Arlington Heights, IL  
60005

**[8] Silicon Valley**  
4935 Southfront Road, Suite F  
Livermore, CA  
94550

## Festo Regional Contact Center

### Canadian Customers

Commercial Support:  
Tel: 1 877 GO FESTO (1 877 463 3786)  
Fax: 1 877 FX FESTO (1 877 393 3786)  
Email: festo.canada@ca.festo.com

Technical Support:  
Tel: 1 866 GO FESTO (1 866 463 3786)  
Fax: 1 877 FX FESTO (1 877 393 3786)  
Email: technical.support@ca.festo.com

### USA Customers

Commercial Support:  
Tel: 1 800 99 FESTO (1 800 993 3786)  
Fax: 1 800 96 FESTO (1 800 963 3786)  
Email: customer.service@us.festo.com

Technical Support:  
Tel: 1 866 GO FESTO (1 866 463 3786)  
Fax: 1 800 96 FESTO (1 800 963 3786)  
Email: product.support@us.festo.com